



# Single Port USB PD Controller for Source Only, AEC-Q100 Qualified

#### **DESCRIPTION**

The MPQ5031 is a USB power delivery controller compatible with Type-C 2.0 and USB PD3.0 specifications. It targets DFP (provider) applications, such as charging-only USB PD ports and USB hubs.

The device is backward compatible, supporting DCP schemes for Quick Charge 3.0, battery charging specifications (BC1.2), Apple divider mode, Huawei FCP, and 1.2V/1.2V mode without outside user interaction. It also supports BC1.2 CDP handshaking. The I<sup>2</sup>C interface and GPIO pins provide good communication with an external power converter.

The MPQ5031 supports up to 100W PD power and PPS as well. It can flexibly configure the PDO list, select slave devices, configure charging protocols, and set the protection mode.

Two NTC pins can be used to monitor for abnormal temperature rise, such as on the Type-C receptacle and PCB board. Power sharing functionality supports smart power budget management between two USB PD ports. PDO capability is reduced when the car battery voltage is low. High-voltage I/O pins support short to battery and short to VBUS protection for the DC/DC converter.

The MPQ5031 is available in a QFN-20 (4mmx4mm) package with wettable flanks.

#### **FEATURES**

- Supports a 3.3V to 21V Bus Voltage Range
- 4.6V to 5.5V VCC Supply Voltage Range
- Integrated Physical Layer for BMC
- Integrated Protocol Layer
- Integrated Policy Engine
- Low Standby I<sub>Q</sub>: 100µA
- Supports One Type-C DFP Port with USB PD3.0 and PPS
- Supports DCP Schemes for BC1.2, 3A Divider, and 1.2V/1.2V Mode
- Supports QC3.0, Huawei FCP
- VBUS Isolation N-Channel MOSFET Driver
- EN Off Timer Up to 120 Minutes
- I<sup>2</sup>C Master/Slave Interface and Interrupt
- Load-Shedding with NTC or Battery Low Detection Function
- High-Voltage Pins for CC1, CC2, DP, and DM
- Integrated High-Voltage V<sub>CONN</sub> Supply Power Switch
- Passed 60W USB-IF PPS Certification with the MPQ4230 (TID: 2313)
- Passed 100W USB-IF PPS Certification with the MPQ4214 (TID: 2316)
- Available in a QFN-20 (4mmx4mm) Package with Wettable Flanks
- Available in Automotive AEC-Q100 Grade 1

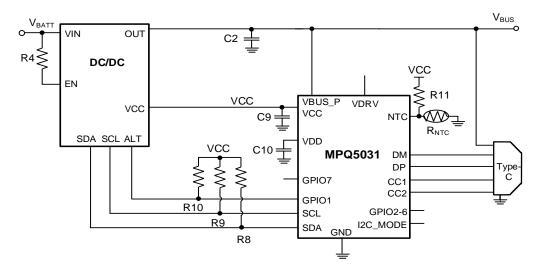
### **APPLICATIONS**

- USB Power Delivery (Provider) Charging Ports
- USB PD Hubs

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# **TYPICAL APPLICATION**



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#### ORDERING INFORMATION

Part Number*	Package	Top Marking	MSL
MPQ5031GRE-0001-AEC1			
MPQ5031GRE-0002-AEC1			
MPQ5031GRE-0003-AEC1	QFN-20		
MPQ5031GRE-0004-AEC1	(4mmx4mm)	See Below	1
MPQ5031GRE-0013-AEC1	(411111114111111)		
MPQ5031GRE-0015-AEC1			
MPQ5031GRE-xxxx-AEC1**			
EVKT-MPQ5031	-	-	-

<sup>\*</sup> For Tape & Reel, add suffix -Z (e.g. MPQ5031GRE-xxxx-AEC1-Z).

#### **TOP MARKING**

**MPSYWW** 

MP5031

LLLLLL

 $\mathbf{E}$ 

MPS: MPS prefix Y: Year code WW: Week code MP5031: Part number LLLLLL: Lot number E: Wettable lead flank

#### **EVALUATION KIT EVKT-MPQ5031**

EVKT-MPQ5031 kit contents (items listed below can be ordered separately):

#	Part Number	Item	Quantity
1	EVQ5031-4230-RE-00A	MPQ5031 + MPQ4230 evaluation board.	1
2	EVKT-USBI2C-02 bag	Includes USB to I <sup>2</sup> C communication interface, one USB cable, and one ribbon cable.	1
3	MPQ5031GRE-0000- AEC1	IC with default configuration. Can be used for OTP configurations.	2

Order directly from MonolithicPower.com or our distributors.

<sup>\*\* &</sup>quot;xxxx" is the configuration code identifier for the register setting stored in the OTP. Each "x" can be a hexadecimal value between 0 and F.



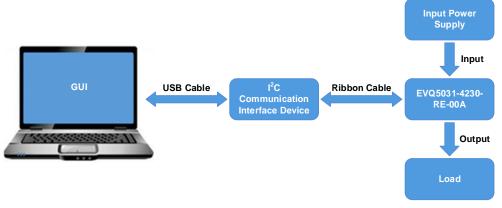
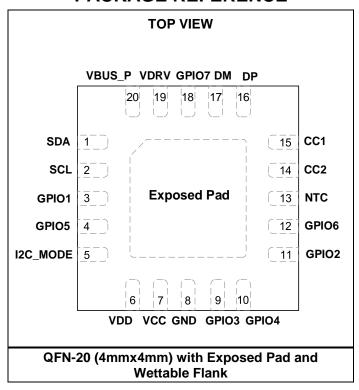


Figure 1: EVKT-MPQ5031 Evaluation Kit Set-Up

### **PACKAGE REFERENCE**



12/15/2020



# **PIN FUNCTIONS**

Pin #	Name	I/O	Description
1	SDA	Bidirectional	I <sup>2</sup> C data line.
2	SCL	Bidirectional	I <sup>2</sup> C clock signal input. When the MPQ5031 is selected as the master, SCL is an output pin.
3	GPIO1	Bidirectional	<b>General purpose I/O 1.</b> See the GPIO register section on page 34 for more details.
4	GPIO5	Bidirectional	<b>General purpose I/O 5.</b> See the GPIO register section on page 35 for more details.
5	I2C_MODE	Input	l²C operation mode setting. Float or pull the I2C_MODE pin low to set the MPQ5031 as the I²C master. Pull this pin high to set the MPQ5031 as an I²C slave. When the MPQ5031 is set to I²C slave mode, the slave functions on GPIO5 and GPIO6 are disabled. Only pin 1 and pin 2 (SDA and SCL) are the I²C slave entrance. This pin has an internal 1MΩ pull-down resistor.
6	VDD	Output	Internal 1.8V LDO regulator output. Decouple with 0.47µF capacitor.
7	VCC	Input	<b>5V power supply for all internal circuitry.</b> The MPQ5031 operates from a 4.5V to 5.5V input voltage. A 4.7 $\mu$ F ceramic capacitor (C <sub>IN</sub> ) must be used to supply power to the internal circuitry, including VCONN.
8	GND	N/A	Ground.
9	GPIO3	Bidirectional	<b>General purpose I/O 3.</b> See the GPIO register section on page 34 for more details.
10	GPIO4	Bidirectional	<b>General purpose I/O 4.</b> See the GPIO register section on page 33 for more details.
11	GPIO2	Bidirectional	<b>General purpose I/O 2.</b> See the GPIO register section on page 34 for more details.
12	GPIO6	Bidirectional	<b>General purpose I/O 6.</b> See the GPIO register section on page 35 for more details.
13	NTC	Input	<b>External temperature-sense pin.</b> See the I <sup>2</sup> C register description on page 34 for the NTC trigger response.
14	CC2	Bidirectional	<b>Configuration channel (CC).</b> CC2 is used for the discovery, configuration, and management of connections across a USB Type-C cable.
15	CC1	Bidirectional	<b>Configuration channel (CC).</b> CC1 is used for the discovery, configuration, and management of connections across a USB Type-C cable.
16	DP	Bidirectional	<b>D+ data line to USB connector.</b> The DP and DM pins are the input/output used for handshaking with portable devices.
17	DM	Bidirectional	<b>D- data line to USB connector.</b> The DP and DM pins are the input/output used for handshaking with portable devices.
18	GPIO7	Bidirectional	<b>General purpose I/O 7.</b> See the GPIO register section on page 35 for more details.
19	VDRV	Output	<b>External N-Channel MOSFET gate driver signal.</b> When the sink is attached, VDRV drives the external N-channel MOSFET to turn on. Then power flows from the DC/DC output to the sink. When the sink is detached, VDRV drives the external N-channel MOSFET to turn off to isolate the power path.
20	VBUS_P	Input	Bus voltage sensing and discharge pin.
Exposed pad	N/A	N/A	Exposed pad. Connect to ground when designing the PCB layout.



# ABSOLUTE MAXIMUM RATINGS (1) VBUS P .....-0.3V (-5V for <10ns) to +24V VDRV ......VBUS\_P + 5V VDD.....-0.3V to +3V DM, DP, CC1, CC2..... .....-0.3V (-5V for <10ns) to +24V GPIO4, GPIO6, NTC .....-0.3V to +5.5V All other pins.....-0.3V to +6V Continuous power dissipation ( $T_A = 25$ °C) (2) QFN-20 (4mmx4mm)......2.1W Junction temperature .......150°C Storage temperature.....-65°C to +150°C ESD Ratings Human body model (HBM) .....±2kV Charged device model (CDM).....±750V Recommended Operating Conditions (3) Power supply to VCC...... 5V/25mA Operating junction temp (T<sub>J</sub>) .... -40°C to +125°C

#### Notes:

- 1) Exceeding these ratings may damage the device.
- 2) The maximum allowable power dissipation is a function of the maximum junction temperature,  $T_J$  (MAX), the junction-to-ambient thermal resistance,  $\theta_{JA}$ , and the ambient temperature,  $T_A$ . The maximum allowable continuous power dissipation at any ambient temperature is calculated by  $P_D$  (MAX) =  $(T_J$  (MAX)  $T_A$ ) /  $\theta_{JA}$ . Exceeding the maximum allowable power dissipation can cause excessive die temperature, and the device may go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- The device is not guaranteed to function outside of its operating conditions.
- 4) Measured on JESD51-7, 4-layer PCB. The value of θ<sub>JA</sub> given in this table is only valid for comparison with other packages and cannot be used for design purposes. These values were calculated in accordance with JESD51-7 and simulated on a specified JEDEC board. They do not represent the performance obtained in an actual application.



# **ELECTRICAL CHARACTERISTICS**

Parameter	Symbol	Condition	Min	Тур	Max	Units
Standby supply current	Іѕтв	VCC current, unattached		100		μΑ
Supply current (on)	I <sub>ON</sub>	CC1 to GND with $5.1k\Omega$ Rd (as defined by USB Type-C Cable and Connector Specification Revision 2.0, which can be downloaded from the official USB website at https://usb.org/).		3.5	4.5	mA
Thermal shutdown (5)	T <sub>OTP_R</sub>			150		°C
Thermal hysteresis (5)	T <sub>OTP_HYS</sub>			20		°C
VDD regulator	$V_{DD}$		1.7	1.8	1.9	V
VDD load regulation	$V_{DD\_REG}$	$I_{DD} = 5mA$		3		%
VCC UVLO rising threshold	Vcc_rs		4	4.3	4.6	V
VCC UVLO threshold hysteresis	Vcc_hys			350		mV
VBUS_P_UV falling threshold	V <sub>BUS_P_UV</sub>	I <sup>2</sup> C set VBUS_UV_THD = 0b	2.79	2.97	3.15	V
GPI07						
DISCHG output high	V <sub>DIS_</sub> HIGH	Discharge turn-on, 50kΩ load		4.4		V
DISCHG output low	R <sub>DIS_LOW</sub>			3.3		kΩ
ADJ sink current	I <sub>ADJ</sub>	GPIO3_ISENS+ = 1.5V	1	2	3	μA
EN_OUT_MID	VEN_OUT_MID	100kΩ, pull-up resistor to 12V	0.8	1	1.2	V
EN_OUT high	Ven_out_h	Open drain, 100kΩ, pull-up resistor to VCC	4.5			V
EN_OUT low	V <sub>EN_OUT_L</sub>				0.4	V
GPIO5, GPIO6	•	,		l	l	l
VBUS_UV_FIXPDO falling threshold	VBUS_UVFIX_	VBUS = 5V	0.91	0.96	1.01	V
IPWM duty cycle	IPWM <sub>DUTY</sub>	4.7kΩ, pull-up resistor to VCC, 3A PDO		50		%
SYNC_OUT1 frequency	f <sub>SYNC1</sub>	4.7kΩ, pull-up resistor to VCC		450		kHz
SYNC_OUT2 frequency	f <sub>SYNC2</sub>	4.7kΩ, pull-up resistor to VCC		450		kHz
I <sup>2</sup> C_SLV_SDA/SCL frequency	fi2C_SLV_SDA_ SCL	4.7kΩ, pull-up resistor to VCC		400		kHz
VSEL2 output low	V <sub>SEL_LOW</sub>	100kΩ to VCC			0.4	V
GPIO4, GPIO3						
EN UVLO rising threshold	V <sub>EN_H</sub>		1.33	1.43	1.53	V
EN UVLO falling hysteresis voltage	V <sub>EN_L</sub>			220		mV
EN_OFF_DELAY	ten_off_delay	EN_OFF_TIMER = 010b		22		min
VBATT low falling threshold	VBATT_LOW_F	Set GPIO4 = 11b	1.07	1.12	1.17	V
VBATT low rising threshold	V <sub>BATT_LOW_R</sub>	Set GPIO4 = 11b	1.12	1.18	1.24	V



Parameter	Symbol	Condition	Min	Тур	Max	Units
ATTACH output high	V <sub>ATTACH_HIGH</sub>		4.5			V
ATTACH output low	Vattach_low	Sink is attached			0.4	V
IPWM duty cycle	IPWM <sub>DUTY</sub>	4.7kΩ, pull-up resistor to VCC, 3A PDO		50		%
Plug orientation (POL) output low	V <sub>POL_L</sub>	CC1 = 5.1kΩ			0.4	V
POL output high	V <sub>POL_</sub> H	CC2 = $5.1k\Omega$ , $10k\Omega$ , pull-up resistor to VCC	4.5			V
GPIO2	•					
Power share input low	V <sub>PS_LOW</sub>	10kΩ pull-up resistor to VCC			0.4	V
Power share input high	V <sub>PS_H</sub>	10kΩ pull-up resistor to VCC	3			V
POL output low	V <sub>POL_L</sub>	CC1 = 5.1kΩ			0.4	V
POL output high	V <sub>POL_</sub> H	CC2 = $5.1k\Omega$ , $10k\Omega$ , pull-up resistor to VCC	4.5			V
QC_12 pull low resistance	R <sub>QC_12</sub>	DP/DM enter QC 12V		8		Ω
I2C_MODE						
Logic high threshold	V <sub>I2C_H</sub>	Slave mode	1	1.2	1.4	V
Hysteresis	V <sub>12C_H_HYS</sub>			100		mV
Resistance	R <sub>12C_MODE</sub>			1		МΩ
GPIO1						
VSEL1 pull low resistance	R <sub>VSEL1</sub>	12V PDO is selected		100		kΩ
VSEL1 output high	V <sub>SEL_HIGH</sub>	100kΩ to VCC	4.5			V
INT logic high	V <sub>INT_HIGH</sub>		4.5			V
INT logic low	V <sub>INT_LOW</sub>				0.4	V
Leakage	I <sub>INT_LKG</sub>				1	μΑ
PDO_SEL_OUTPUT (Config	ure SLAVE_D	DEVICE_SEL = 101b)				
PDO2 to PDO3 SEL_OUT pull low resistance	R <sub>PDO2_LOW</sub>			7		Ω
PDO2-4 SEL OUT leakage	V <sub>PDO_HIGH</sub>	5V PDO is selected			1	μΑ
NTC, NTC2						
External thermal-sense trip threshold	V <sub>NTC_R</sub>	$R_P = 47k\Omega, R_{NTC} = 4.72k\Omega (100^{\circ}C)$	7.5	9.1	10.5	%VCC
External thermal-sense recovery threshold	V <sub>NTC_F</sub>	$R_P = 47k\Omega, R_{NTC} = 9.45k\Omega (80^{\circ}C)$		16.7		%VCC
Gate Drive (VDRV)				•		
Gate drive voltage	V <sub>DRV</sub>	V <sub>DRV</sub> - V <sub>BUS_P</sub>	-	4.85		V
Gate drive voltage at 15µA	V <sub>DRV_1</sub>	Isource = 15µA		4.4		V
Pull-down resistor	R <sub>PULL_DOWN</sub>			5		kΩ
BC1.2 DCP Mode	T			1		T
DP and DM short resistance	R <sub>DP_DM_SHORT</sub>	$V_{DP} = 0.8V$ , $I_{DM} = 1mA$ , $T_{J} = 25$ °C		25	40	Ω



Parameter	Symbol	Condition	Min	Тур	Max	Units
Divider Mode	•		·			
DP output voltage	V <sub>DIVIDER_DP</sub>	Vout = 5V	2.55	2.75	2.95	V
DM output voltage	V <sub>DIVIDER_DM</sub>	Vout = 5V	3.35	3.6	3.85	V
DP output impedance	R <sub>DIVIDER_DP</sub>			22		kΩ
DM output impedance	R <sub>DIVIDER_DM</sub>			22		kΩ
1.2V/1.2V Mode						
DP/DM output voltage	V <sub>DP_DM_1.2V</sub>	Vout = 5V	1.05	1.20	1.35	V
DP/DM output impedance	R <sub>DP_DM_1.2V</sub>			300		kΩ
Quick Charge 3.0 Mode						
DP/DM low voltage	V <sub>QC_LOW</sub>		0.2	0.3	0.4	V
DP/DM high voltage	Vqc_ніgн		1.8	2	2.2	V
DP output impendence	R <sub>DP_QC</sub>			350	1500	kΩ
DM output impendence	R <sub>DM_QC</sub>			20		kΩ
DM low glitch time (5)	t <sub>GLITCH_DM</sub>			10		ms
DP high glitch time	tGLITCH_DP		1000		1500	ms
Output voltage change glitch time (5)	tglitch_v_ CHANGE		20	40	60	ms
Bus voltage step (5)	V <sub>BUS_CONT_STEP</sub>		150	200	250	mV
Time for VBUS to discharge to 5V when DP < 0.6V (5)	t <sub>V_UNPLUG</sub>				500	ms
FCP Mode						
DM Tx high voltage	V <sub>FCPT_H</sub>	$R_{LOAD} = 15k\Omega$	2.55		5	V
DM Tx low voltage	V <sub>FCPT_L</sub>	$R_{LOAD} = 15k\Omega$			0.4	V
DM Rx high voltage	V <sub>FCPR</sub> H		1.5		5	V
DM Rx low voltage	V <sub>FCPR_L</sub>				1	V
DM pull-low resistance (5)	R <sub>LD_D</sub> .			15		kΩ
Unit interval of PHY (5)	UI	f <sub>CLK</sub> = 125kHz	144	160	176	μs
CDP Mode (I <sup>2</sup> C set CDP_EN	=1)					
DM CDP output voltage	V <sub>DM_SRC</sub>	V <sub>DP</sub> = 0.6V, DM_SINK = 250μA	0.5	0.6	0.7	V
DP rising lower window threshold for V <sub>DM_SRC</sub>	V <sub>DAT_REF</sub>		0.25	0.35	0.45	V
DP rising lower window threshold hysteresis	V <sub>DAT_REF_HYS</sub>			50		mV
DP rising upper window threshold for V <sub>DM_SRC</sub>	VLGC_SRC		0.8	0.95	1.1	V
DP rising upper window threshold hysteresis	V <sub>LGC_SRC_HYS</sub>			80		mV
USB Type-C - CC1 and CC2	pins					
CC pull-up current 1	I <sub>RP1</sub>	VBUS = 5V/3A, T <sub>J</sub> = 25°C	304	330	356	μA
CC pull-up current 2	I <sub>RP2</sub>	VBUS = 5V/1.5A, T <sub>J</sub> = 25°C	162	180	198	μA
CC voltage to enable VCONN for 3A Type-C mode	V <sub>RA1</sub>	T <sub>J</sub> = 25°C			0.75	V



Parameter	Symbol	Condition	Min	Тур	Max	Units
CC voltage to enable V <sub>BUS</sub> for 3A Type-C mode	V <sub>RD1</sub>	T <sub>J</sub> = 25°C	0.85		2.45	V
CC detach threshold for 3A Type-C mode	V <sub>OPEN1</sub>	T <sub>J</sub> = 25°C	2.75			V
CC voltage falling debounce timer	t <sub>CC_DEBOUNCE</sub>	VBUS enable deglitch	100	150	200	ms
CC voltage rising debounce timer	t <sub>PD_DEBOUNCE</sub>	VBUS disable deglitch	5	10	15	ms
V <sub>CONN</sub> output power	P <sub>V_CONN</sub>	VCC supplies V <sub>CONN</sub>	0.1			W
USB PD						
Unit interval	tuı	T <sub>J</sub> = 25°C	3.0	3.35	3.7	μs
Transmitter			·			
End drive BMC (5)	<b>t</b> EDBMC				23	μs
Fall time (5)	t <sub>FALL</sub>		300			ns
Rise time (5)	t <sub>RISE</sub>		300			ns
Hold low BMC (5)	tньвмс		1			μs
Logic high voltage	V <sub>L</sub> H		1	1.15	1.3	V
Logic low voltage	V <sub>LL</sub>				100	mV
Output impedance	R <sub>TX</sub>			50		Ω
Receiver (5)			•			•
CC receiver capacitance	Creceiver				600	pF
Transitions for signal detection	NTRANSITION		3			edges
Rx bandwidth limiting filter	t <sub>RX_FILTER</sub>		100			ns
Time Window for Detecting Non-idle	tTRANSITION_ WINDOW		12		20	μs
Receiver input impedance	R <sub>BMC_RX</sub>		1			МΩ
I <sup>2</sup> C Interface Specifications	(5)		•			•
Input logic high	VIL		1.4			V
Input logic low	Vih				0.6	V
Output voltage logic low	V <sub>OUT_L</sub>				0.4	V
SCL clock frequency	fscL			400		kHz
SCL high time	tніgн		60			ns
SCL low time	t <sub>LOW</sub>		160			ns
Data set-up time	t <sub>SU_DAT</sub>		10			ns
Data hold time	thd_dat			70		ns
Set-up time for repeated start	tsu_sta		160			ns
Hold time for a repeated start condition	t <sub>HD_STA</sub>		160			ns
Bus free time between a start and a stop condition	t <sub>BUF</sub>		160			ns



 $V_{CC} = 5V$ ,  $T_J = -40$ °C to +125°C, typical value is tested at  $T_J = 25$ °C, unless otherwise noted.

Parameter	Symbol	Condition	Min	Тур	Max	Units
Set-up time for a stop condition	<b>t</b> su.sto		160			ns
SCL and SDA rise time	t <sub>R</sub>		10		300	ns
SCL and SDA fall time	t⊧		10		300	ns
Pulse width of suppressed spike	t <sub>SP</sub>		0		50	ns
Capacitance bus for each bus line	Св				400	pF

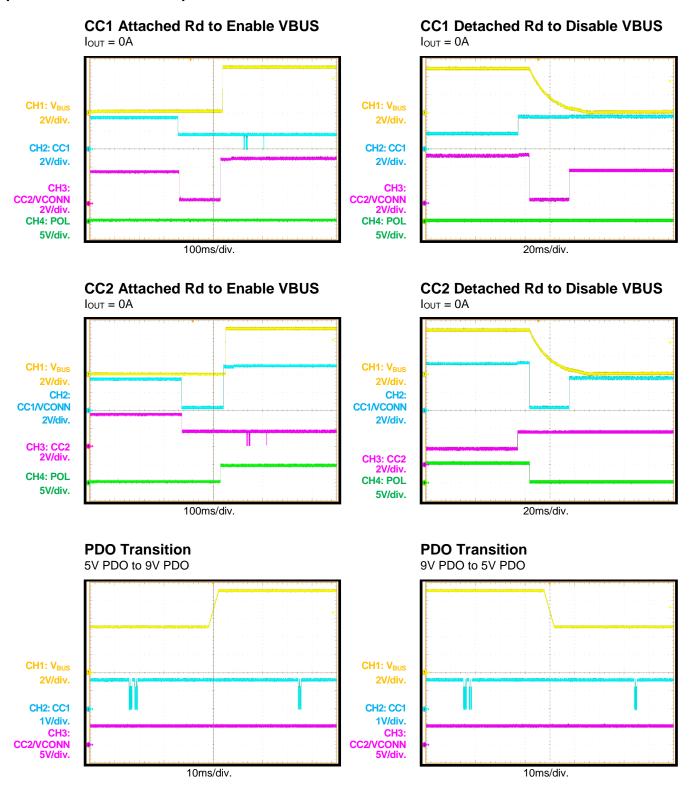
#### Note:

5) Guaranteed by characterization.



#### TYPICAL PERFORMANCE CHARACTERISTICS

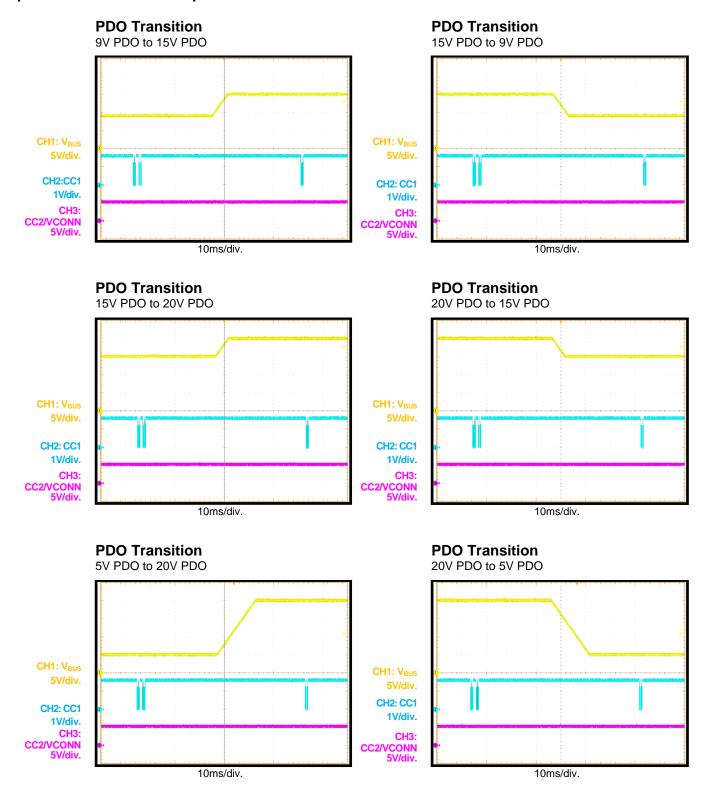
 $V_{CC}$  = 5V,  $V_{BUS}$  = 5V to 20V,  $T_A$  = 25°C, unless otherwise noted. Connect the MPQ5031's VBUS\_P pin to the MPQ4230's output.



# TYPICAL PERFORMANCE CHARACTERISTICS (continued)



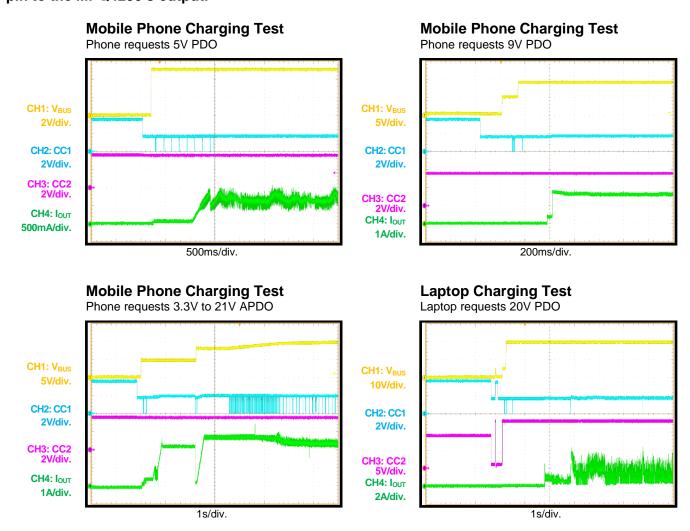
 $V_{CC}$  = 5V,  $V_{BUS}$  = 5V to 20V,  $T_A$  = 25°C, unless otherwise noted. Connect the MPQ5031's VBUS\_P pin to the MPQ4230's output.



# TYPICAL PERFORMANCE CHARACTERISTICS (continued)



 $V_{\text{CC}}$  = 5V,  $V_{\text{BUS}}$  = 5V to 20V,  $T_{\text{A}}$  = 25°C, unless otherwise noted. Connect the MPQ5031's VBUS\_P pin to the MPQ4230's output.





# **FUNCTIONAL BLOCK DIAGRAM**

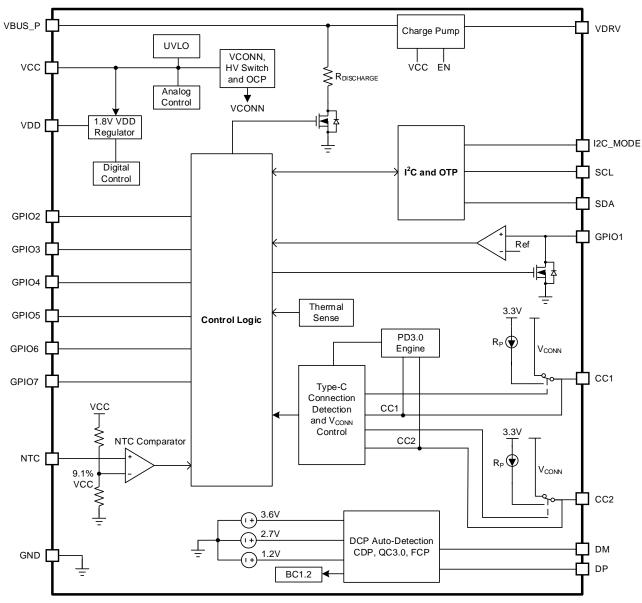


Figure 2: Functional Block Diagram



#### **OPERATION**

#### **Under-Voltage Lockout (UVLO)**

Under-voltage lockout (UVLO) protects the chip from operating at an insufficient supply voltage. The MPQ5031's UVLO comparator monitors the VCC input voltage.

#### **VCC and VDD Regulator**

The VCC pin is biased by an external 5V supply (e.g. the DC/DC converter's VCC pin). The VCC pin must have a decoupling capacitor between  $1\mu\text{F}$  and  $10\mu\text{F}$ .

The 1.8V internal VDD regulator uses VCC as the input. The VDD pin powers most of the digital circuitries, and requires a  $0.47\mu F$  decoupling capacitor.

# **Charging Mode Auto-Detection Legacy USB 2.0 Mode**

The MPQ5031 integrates a USB dedicated charging port auto-detection function that can recognize most mainstream portable devices. It supports the following charging schemes:

- USB Battery Charging Specification BC1.2/ Chinese Telecommunications Industry Standard YD/T 1591-2009
- Apple 3A divider mode
- 1.2V/1.2V mode
- QC3.0 Class A (3.3V to 12V)
- Huawei FCP Class A

The auto-detection function is a state machine that supports all of the above DCP charging schemes, starting in divider mode. If a device compliant with divider mode is attached, the MPQ5031 remains in divider mode. Then 3.6V is applied to the DM pin, and 2.7V is applied to the DP pin.

If a device compliant with BC1.2 or YD/T 1591-2009 is attached, the MPQ5031 operates in 1.2V/1.2V and BC1.2 DCP mode. DM and DP are shorted together with a resistance below  $40\Omega$ . The MPQ5031 remains in that mode until the device releases the data line. Then the device returns to divider mode.

When a QC3.0 or FCP device (without PD protocol) is attached, the MPQ5031 automatically enters high-voltage quick charge mode.

The MPQ5031 supports BC1.2 charging data

port (CDP) handshaking as well, which can be enabled by the I<sup>2</sup>C. DCP mode should be disabled (LEGACY\_CHARGING\_MODE\_SEL = 11b) when the CDP function is selected.

If a USB PD contract is established once the sink is attached, QC3.0 functionality is disabled, but BC1.2 short mode is still enabled.

#### **USB Type-C Port**

The USB Type-C receptacle, plug, and cable solution incorporates a configuration process to detect a downstream-facing port (DFP) to upstream-facing port (UFP) connection for  $V_{\text{BUS}}$  management, and to determine the host-to-device relationship.

Initially, DFP-to-UFP attachment is detected by a host (DFP) when one of the CC pins at its USB Type-C receptacle senses a specified resistance to GND. Subsequently, UFP-to-DFP detachment is detected when the CC pin that was terminated at its USB Type-C receptacle is no longer connected to GND.

Power is not applied to the USB Type-C host or hub receptacle ( $V_{\text{BUS}}$  or  $V_{\text{CONN}}$ ) until the DFP detects the presence of an attached device (UFP) port. When a DFP-to-UFP attachment is detected, the DFP enables power to the receptacle and begins normal USB operation with the attached device. When a DFP-to-UFP detachment is detected, the port sourcing  $V_{\text{BUS}}$  removes power.

The MPQ5031 is a DFP (provider only), and its power supply capability is rated at 5V/3.0A by default.  $V_{\text{CONN}}$  is provided by the DFP to power the cables and electronics in the plug.  $V_{\text{CONN}}$  is provided instead of the CC pin if the CC pin is not connected to the cable's configuration channel (CC) wire.  $V_{\text{CONN}}$  has a maximum power output of 100mW.

 $V_{CONN}$  is disabled until  $R_A$  is detected.  $R_A$  is a pull-down resistor connected from the CC pin to GND, and its resistance should be below 1.2k $\Omega$ .

#### **USB Power Delivery**

In USB power delivery (PD), pairs of directly attached ports negotiate voltage, current, and/or direction of power flow over the USB cable by



using the CC wire as the communication channel. The mechanisms that are implemented operate independently of other USB methods that are used to negotiate power.

Type-C connectors can support the CC wire as the communication channel. The USB PD engine is disabled until a valid Type-C connection is established. Figure 3 shows a USB PD communication stack.

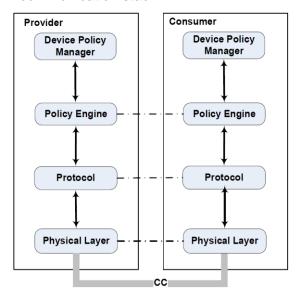


Figure 3: USB PD Communication Stack

#### **DFP Commands**

Table 1, Table 2, and Table 3 list the MPQ5031's supported commands. Table 1 lists the control messages.

**Table 1: Control Message** 

	=	
Transmitted Message	Received Message	
Accept	Get_PPS_Status	
Get_Sink_Cap	Get_Source_Cap	
Get_Sink_Cap_	Get_Source_Cap_	
Extended	Extended	
Get_Status	Get_Status	
GoodCRC	GoodCRC	
GotoMin	Not_Supported	
Not_Supported	Reject	
PS_RDY	Soft_Reset	
Reject	VCONN_Swap	
Soft_Reset		

Table 2 lists the different data messages.

Table 2: Data Messages

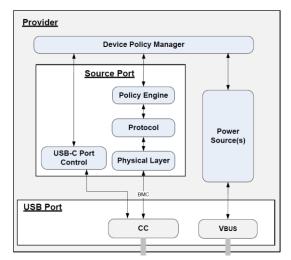
Transmitted Message	Received Message	
Source_Capabilities	Sink_Capabilities	
BIST	Request	
Alert	BIST	
	Alert	

Table 3 lists the extended messages.

**Table 3: Extended Messages** 

Transmitted Message	Received Message
Status	
PPS_Status	
Source_Capabilities_	
Extended	

The MPQ5031 also supports soft reset, hard reset, and cable discovery for VDM signals. Figure 4 shows the device policy manager.



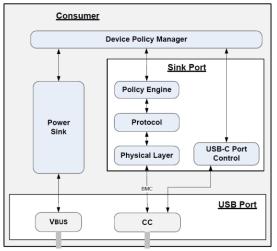


Figure 4: Device Policy Manager



#### **PD Contract Handshake**

Figure 5 shows the MPQ5031's PD contract handshake sequence.

#	CH	OS	Power	Data	Cable Plug	Туре
0	CC2	SOP'			UFP or DFP	Vendor_Defined
1	CC2	SOP'			Cable Plug	GoodCRC
2	CC2	SOP'			Cable Plug	Vendor_Defined
3	CC2	SOP'			UFP or DFP	GoodCRC
4	CC2	SOP	Source	DFP		Source_Capabilities
5	CC2	SOP	Sink	UFP		GoodCRC
6	CC2	SOP	Sink	UFP		Request
7	CC2	SOP	Source	DFP		GoodCRC
8	CC2	SOP	Source	DFP		Accept
9	CC2	SOP	Sink	UFP		GoodCRC
10	CC2	SOP	Source	DFP		PS_RDY
11	CC2	SOP	Sink	UFP		GoodCRC

Figure 5: PD Contract Handshake

#### **VBUS and VCONN Discharge**

When the sink is detached or a hard reset occurs, the MPQ5031 sends a command to turn off the DC/DC regulator's output voltage, and VBUS P's 200Ω discharge resistor turns on for 200ms. The GPIO7 pin can also be used to control an external MOSFET to discharge the output voltage for 200ms. Meanwhile, the VCONN voltage is discharged with a  $1k\Omega$ resistor for 30ms.

#### **VBUS Under-Voltage (UV) Detection**

When a DC/DC converter with an I<sup>2</sup>C interface is under-voltage selected. the VBUS detection function is enabled by monitoring PG STATUS. If the VBUS P voltage is <2.97V (or <4.5V) during PPS operation, the VBUS UV bit is set to 1 internally, and a hard reset is triggered.

When a DC/DC converter without an I2C interface is selected, PPS functionality is disabled. In fixed PDO operation, GPIO5 can be configured to VBUS UV FIXPDO. For this function, connect GPIO5 to VBUS with a 1/5 resistor divider to detect the VBUS voltage. Table 4 lists how to set the VBUS UV threshold in a fixed PDO state. When the VBUS voltage is below the threshold, VBUS\_UV\_FIXPDO is set to 1 internally, and a hard reset is triggered.

Table 4: VBUS UV Threshold (Only Valid for DC/DC Converters without I<sup>2</sup>C)

Sink Requested	VBUS_UV_ FIXPDO Threshold (V)	VBUS UV threshold (V)		
Default, Vout = 5V	0.96	4.8		
Vout = 9V	1.743	8.715		
V <sub>OUT</sub> = 15V	2.938	14.69		
V <sub>OUT</sub> = 20V	3.88	19.4		

Figure 6 shows a VBUS UV example.

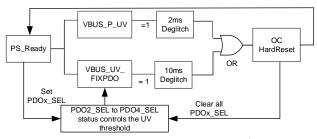


Figure 6: VBUS UV Detection for Non-I<sup>2</sup>C DC/DC ApplicationsStart-Up and Shutdown Timing

The GPIO3, GPIO4, and GPIO6 pins can be configured to be the EN input function that controls when the MPQ5031 is on or off.

If the MPQ5031's VCC exceeds 4.3V and the GPIOx EN pin is pulled high, the PD engine can be enabled. The MPQ5031's start-up time should begin after the DC/DC converter start-up time, and its shutdown time should be before the converter's shutdown time (see Figure 7).

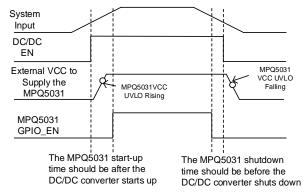


Figure 7: MPQ5031 Start-Up and Shutdown **Timing** 

When the MPQ421x, MPQ423x, MPQ426x or MPQ4272 is used as the DC/DC converter, the converter's 5V LDO output can power the MPQ5031's VCC. If the MP28167-A is selected as the DC/DC converter, an external 5V LDO should be added to power the MPQ5031. The



external 5V LDO's start-up timing should be later than the MP281671-A's timing.

In the MPQ421x, MPQ4272, or MP28167-A PD solution, the MPQ5031's GPIOx\_EN pin should be added to control the PD engine's start-up/shutdown time.

If connecting the MPQ5031 GPIOx\_EN pin to VIN, the input voltage ( $V_{IN}$ ) of the PD's start-up and shutdown sequence can be calculated with Equation (1) and Equation (2), respectively:

$$V_{IN\_ON}(V) = 1.43V \times (R_{DN2} + R_{UP2}) / R_{DN2}$$
 (1)

$$V_{IN\_OFF}(V) = 1.21V \times (R_{DN2} + R_{UP2}) / R_{DN2}$$
 (2)

Figure 8 shows the MPQ5031's start-up time schematic.

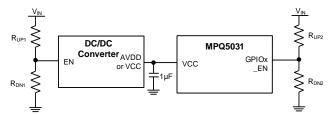


Figure 8: MPQ5031 Start-Up Time Schematic

Table 5 lists the  $V_{\text{IN}}$  start-up and shutdown thresholds.

Table 5: VIN Start-Up/Shutdown Threshold

	DC/DC EN Divider (kΩ)	MPQ5031 EN Divider (kΩ)	DC/DC Start-Up/ Shutdown (V)	MPQ5031 Start-Up/ Shutdown (V)
MPQ5031 + MPQ4214	100/30	100/28.4	5.85/5.07	6.47/5.47
MPQ5031 + MPQ4272	100/39	100/28.4	5.7/4.9	6.47/5.47

#### **EN Off Delay Timer**

The GPIO3 pin can be configured for EN\_OFF\_DELAY\_OUT functionality. When EN is high, the IC is enabled immediately. When the external EN off signal is received, EN\_OFF\_DELAY\_OUT (GPIO3) remains high for 22min (EN\_OFF\_TIMER = 010b) to enable the upstream DC/DC converter. Once the 22min delay time completes, the USB PD engine is disabled immediately and CLK is disabled after a 200ms delay (see Figure 9). Figure 10 on page 20 shows the timing sequence.

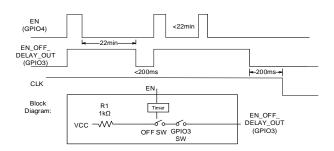


Figure 9: EN Off Timer

If EN\_OFF\_DELAY functionality is not required, configure the GPIO3 for a function that is not EN\_OFF\_DELAY\_OUT.



#### **State Machine and Timing Sequence**

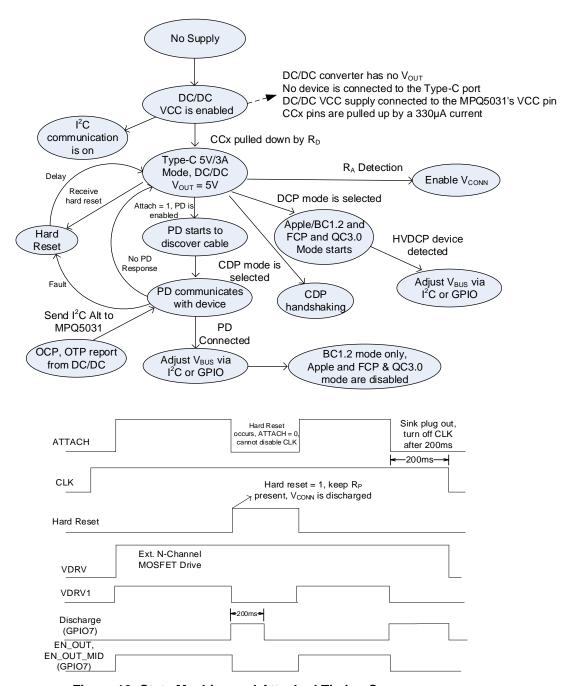


Figure 10: State Machine and Attached Timing Sequence



#### **VCONN Over-Current Protection (OCP)**

The VCC to  $V_{CONN}$  switch has a  $20\Omega$  resistance and a 50mA over-current protection (OCP) threshold. When  $V_{CONN}$  OCP is triggered, the  $V_{CONN}$  output latches off. The following actions can re-enable  $V_{CONN}$ :

- Cycling power on VIN and EN
- A hard reset
- Detaching and reattaching the USB Type-C device

#### Bidirectional I<sup>2</sup>C Interface

The MPQ5031's SDA and SCL pins support both I<sup>2</sup>C master and I<sup>2</sup>C slave functions. When cooperating with an external buck-boost converter (e.g. the MPQ4230), the MPQ5031 should operate in I<sup>2</sup>C master mode. When a user

wants to configure the MPQ5031's I<sup>2</sup>C register, I<sup>2</sup>C slave mode should be selected.

Float I2C\_MODE or pull it to GND to set the MPQ5031 to I<sup>2</sup>C master mode. Pull I2C\_MODE to VCC to set the MPQ5031 to I<sup>2</sup>C slave mode. In I<sup>2</sup>C slave mode (I2C\_MODE = VCC), the digital CLK is always on. The I<sup>2</sup>C register and I<sup>2</sup>C functionality are active once VCC is ready. The user does not need to wait for a Type-C sink to be attached.

The GPIO5 and GPIO6 pins can be configured as a second I<sup>2</sup>C slave entrance, but an internal clock must be turned on to access full I<sup>2</sup>C functionality. SDA, SCL, GPIO5, and GPIO6 cannot simultaneously work in I<sup>2</sup>C slave mode (see Table 6).

Table 6: I<sup>2</sup>C Function on Pin 1, Pin 2 and GPIO5, GPIO6

I2C_MODE Input	Pin 1, Pin 2 (SDA, SCL) Function	GPIO5, GPIO6 I <sup>2</sup> C Function	Internal Clock
VCC	In I <sup>2</sup> C slave mode	I <sup>2</sup> C functionality is disabled	Always on
GND	In I <sup>2</sup> C master mode	In I <sup>2</sup> C slave mode.  Must turn on internal clock to access full I <sup>2</sup> C function	Either USB Type-C attachment or writing 0x55AA to register 0x14 can enable the internal clock

#### **Battery Low Detection**

The GPIO4 and GPIO2 pins can be configured as an input battery voltage sense pin. If the battery voltage drops below a certain level (this level is configurable), then the USB PD engine updates the source capability based on the I<sup>2</sup>C control bits VBATT\_LOW\_PULL\_PS\_EN and VBATT\_LOW\_PULL\_NTC\_EN (see Table 7). When the battery voltage recovers, the USB PD engine changes the source capabilities to normal. If VBATT\_LOW\_PULL\_NTC\_EN = 1, the source

capability returns to normal after a 16-second delay.

This function can also be disabled via I<sup>2</sup>C control bits VBATT\_LOW\_PULL\_PS\_EN and VBATT\_LOW\_PULL\_NTC\_EN.

The recommended resistor divider ratio on VBATT\_SENSE pin is 1/10. The internal comparator falling threshold is 1.12V, and the rising threshold is 1.18V with a 20µs deglitch time.

**Table 7: Battery Low Update Source Capability** 

VBATT_LOW_ PULL_PS_EN	0	0	1
VBATT_LOW_ PULL_NTC_EN	0	1	0
Battery Voltage Low	PDO list is based on the PDO_TYPE register setting	Update PDO1 to 5V/2A, other PDOs are disabled	Disable the PDO with a power rating ≥ PWR_SHARE_TO_ PDP



The battery voltage can be calculated with Equation (3):

 $V_{BATT\_LOW}(V) = 1.12V \times (R_{DN} + R_{UP}) / R_{DN}$  (3)

Figure 11 shows the resistor divider.

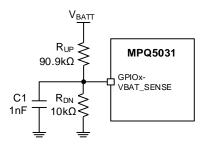


Figure 11: VBATT\_SENSE Divider Resistor

#### **Load-Shedding Entry and Recovery**

When the NTC or NTC2 (NTC2\_PS\_EN = 0) falling threshold is triggered (NTC\_MODE = 0), the Type-C resistor ( $R_P$ ) pull-up current changes

Load-Shedding Exit:

from 330µA to 180µA, regardless of whether there is a PD contract.

When MPQ423x or MPQ426x device is selected (SLAVE\_DEVICE\_SEL = 001b), and it sends an OT\_WARNING signal and a PD contract exists, the Type-C pull-up current ( $R_P$ ) changes from 330 $\mu$ A to 180 $\mu$ A. The Type-C detection threshold then changes accordingly. If a PD contract exists, the USB PD PDO is updated to 5V/2A, and all other PDOs are disabled.

If the NTC or NTC2 voltage recovers to a normal value, and the external DC/DC converter OT\_WARNING = 0 (after a 16-second delay),  $R_P$  changes back to 330 $\mu$ A. If there was originally a PD contract, the MPQ5031 USB PD engine sends the default PDOs again. When NTC2\_PS\_EN = 1 and the NTC2 falling threshold is triggered, the MPQ5031 updates the PDO list based on the PWR\_SHARE\_TO\_PDP setting.

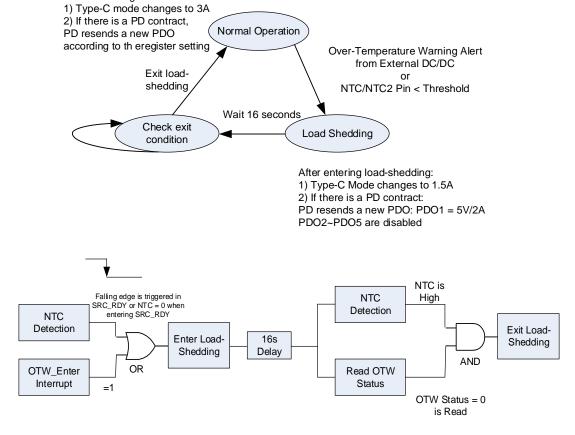


Figure 12: Load-Shedding Logic and State Machine (NTC2 PS EN = 0)



#### **Thermal Shutdown**

Thermal shutdown prevents the chip from operating at exceedingly high temperatures. When the silicon die temperature exceeds 150°C or the NTC/NTC2 falling threshold is triggered (NTC\_MODE = 1), the MPQ5031 resets the USB PD engine and stops the DC/DC converter from switching via I<sup>2</sup>C communication, or by pulling the converter's EN pin low. When the temperature falls below its lower threshold (about 130°C), the chip is enabled for CCx detection. If the sink is attached, the MPQ5031 starts to enable the USB PD engine again.

The I<sup>2</sup>C slave is still operational during thermal shutdown.

#### **Power Sharing Function**

The GPIO2 pin can be configured for power When share input functions. GPIO<sub>2</sub> (POWER SHARE) is pulled low, the USB PD engine disables the PDO if the power rating meets or exceeds PWR SHARE TO PDP, and all PPS APDOs are disabled.

The GPIO3, GPIO5, or GPIO7 pins can be configured for ATTACH indication. If using multiple devices, and the first MPQ5031 (MPQ5031 #1) detects that a sink is attached, it pulls GPIO3 low. Then the second MPQ5031's (MPQ5031 #2) GPIO2 is pulled low at the same time. MPQ5031 #2 disables the PDO with a power rating that is ≥PWR\_SHARE\_TO\_PDP, and all PPS APDOs are disabled.

The GPIO2 pin can also be used for power share output functions. When the MPQ5031's sinkrequested **PDO** power rating is ≥PWR SHARE OUTPUT THLD, GPIO2 is pulled low.

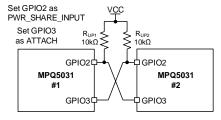


Figure 13: Power-Share Connection between Two MPQ5031s (Cut Total Power to 50%/50%)

#### I<sup>2</sup>C Arbitration

The GPIO3 pin can be configured for I<sup>2</sup>C (I2C ARB) arbitration functions. When

MPQ5031 #1 sends an I<sup>2</sup>C command, it pulls down GPIO3 first. GPIO3 is pulled high again after MPQ5031 #1's I2C command is finished. MPQ5031 #2 always checks the GPIO3 status. and starts to send an I2C command until GPIO3 is released to high (see Figure 14). It is can be used in MPQ4272 reference design.

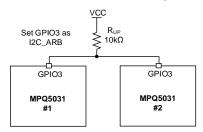


Figure 14: I<sup>2</sup>C Arbitration Connection

#### **CDP Mode**

MPQ5031 The integrates CDP mode handshaking. Set CDP\_EN = 1 to enable CDP mode handshaking, and disable Apple divider mode, FCP, 1.2V/1.2V mode and other DCP DP schemes on and DM (LEGACY CHARGING MODE SEL = 11b) (see Figure 15).

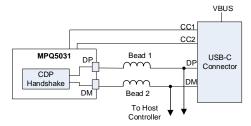


Figure 15: CDP Mode Set-Up

#### Smart Line Drop Compensation

MPQ5031 The has smart line drop compensation when the MPQ423x, MPQ426x or MPQ421x DC/DC converter is attached. Line drop compensation is active in fixed PDO or non-PD conditions. After entering a PPS condition. line drop compensation is disabled. If the other DC/DC converter is selected, the line drop compensation value is determined by the converter's set-up. The MPQ5031 does not disable line drop compensation in a PPS state.

When an MPQ423x or MPQ426x device is selected (SLAVE DEVICE SEL = 001b), the line drop compensation value is determined by the MPQ423x or MPQ426x's set-up. The MPQ5031 disables MPQ423x or MPQ426x line drop compensation after entering PPS.



When an MPQ421x device is selected (SLAVE DEVICE SEL = 000b), the MPQ5031 GPIO3 can be configured for ISENS+ functions to sense the MPQ421x's COMP pin voltage.

GPIO7 can be configured for ADJ functions to sink the 2µA current on the MPQ421x's FB pin when the COMP voltage exceeds a certain voltage.

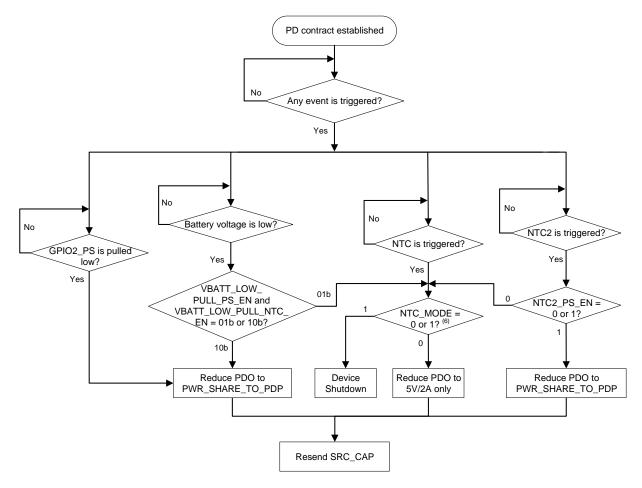


Figure 16: PDO Reduce Logic and State Machine

#### Note:

6) When NTC and PWR\_SHARE\_TO\_PDP events (GPIO2\_PS pulls low, battery voltage low or NTC2) are triggered at the same time, the PDO lists are updated based on the NTC set-up. If NTC MODE = 1, the device shuts down; if NTC MODE = 0, the PDO list is updated to 5V/2A.



#### I<sup>2</sup>C Transfer Data

Every byte put on the SDA line must be 8 bits long. Each byte must be followed by an acknowledge (ACK) bit. The master generates the acknowledge-related clock pulse. The transmitter releases the SDA line (high) during the acknowledge clock pulse. The receiver must pull down the SDA line during the acknowledge clock pulse so that it remains stable (low) during the high period of this clock pulse.

Figure 17 shows the data transfer format. After the start condition (S), a slave address is sent. This address is 7 bits long followed by an 8th data direction bit (R/W). A 0 indicates a transmission (write), while a 1 indicates a request for data (read). A data transfer is always terminated by a stop condition (P) generated by the master. For a master to continue communicating on a bus, it can generate a repeated start condition (Sr) and address another slave without first generating a stop condition.

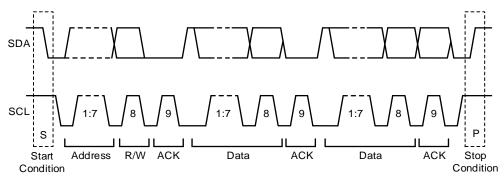


Figure 17: Complete Data Transfer

The MPQ5031 includes a full I<sup>2</sup>C slave controller. The I<sup>2</sup>C slave fully complies with the I<sup>2</sup>C specification requirements. It requires a start condition, valid I<sup>2</sup>C address, register address byte, and data byte for a single data update. After receiving each byte, the MPQ5031 acknowledges the byte by pulling the SDA line

low during the high period of a single clock pulse. A valid I<sup>2</sup>C address then selects the MPQ5031, and the MPQ5031 performs an update on the falling edge of the LSB byte.

Figure 18 shows an example of an I<sup>2</sup>C read and write command.

#### a) I2C Write Word 8 Slave Address Wr A I2C Register Address Α Data Byte Low Data Byte High b) I2C Read Word 8 7 8 Slave Address | Wr A | I2C Register Address | A | S Slave Address Rd A Data Byte Low Α Data Byte High

Figure 18: I<sup>2</sup>C Read and Write



# I<sup>2</sup>C REGISTER MAP

### I<sup>2</sup>C Slave, I2C\_MODE = VCC

Add (Hex)	Name	R/W	D15	D14	D13	D12	D11	D1 0	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
00	PDO_ TYPE	R/W		OTP_SOFTWARE_REVISION_NO (7)						ERVED	PDO 5_EN	PDO 4_EN (7)	PDO 3_EN (7)	PDO 2_EN (7)	PDO5_ TYPE	PDO4_ TYPE	PDO3_ TYPE	PDO2 _TYPE
01	PDO_ V1	R		RESERVED							F	PDO1_\	/OLTA	GE_SE	TTING (5	5V)		
02	PDO_I1	R/W		OTP_SUFFIX_CODE (7)							PDO1	_CURF	RENT_S	SETTIN	G <sup>(7)</sup> (3A	default)		
03	PDO_ V2	R/W					PD	O2_V	OLTAG	SE_SETTI	NG <sup>(7)</sup> (9	9V defa	ult)					
04	PDO_I2	R/W			RESER	RVED					PDO2	_CURF	RENT_S	SETTIN	G <sup>(7)</sup> (3A	default)		
05	PDO_ V3	R/W					PDO	O3_V	OLTAG	E_SETTIN	IG <sup>(7)</sup> (1	5V defa	ault)					
06	PDO_I3	R/W			RESER	RVED					PDO3	_CURF	RENT_S	SETTIN	G <sup>(7)</sup> (3A	default)		
07	PDO_ V4	R/W					PDO	04_V	OLTAG	E_SETTIN	IG <sup>(7)</sup> (2	:0V defa	ault)					
08	PDO_I4	R/W			RESER	VED					PDO4	_CURF	RENT_S	SETTIN	G <sup>(7)</sup> (3A	default)		
09	PDO_ V5	R/W					PDO5_	VOLT	AGE_S	ETTING (	<sup>7)</sup> (3.3V	to 21V	default	)				
0A	PDO_I5	R/W		RESERVED PDO5_CURRENT_SETTING (7) (3A default)														
0B	CTL1	R/W	VBATT _LOW _PULL _PS_ EN <sup>(7)</sup>	LEGACY_ CHARG ING_ MODE_ SEL_1 (7)	NTC2_ PS_EN	CDP_ EN (7)	LEGACY_ CHARG ING_ MODE_ SEL_0 (7)	RESI	SERVED VBATT_ LOW_ PULL_ NTC_EN (7) SERVED NTC_EN (7) SLAVE		SLAVE	AVE_DEVICE_SEL (7)						
0C	CTL2	R/W	HD RST	SEND_ SRC_ CAP	USB SUSP END <sup>(7)</sup>	USB COMM UNICA TE (7)	LP	S (7)			DUCH_ RRENT		TOU TEM	ICH_ 1P <sup>(7)</sup>	UNCU KEXT MSG	RESE RVED	SRC_CAP (7)	VDRV _EN <sup>(7)</sup>
0D	CTL3	R/W	PFM_ PWM	FREQ_ DITHER	EN_	_OFF_TII	MER (7)	GPI	IO4 <sup>(7)</sup>	GI	PIO3 <sup>(7)</sup>			GPIO2	(7)		GPIO1 <sup>(7</sup>	)
0E	CTL4	R/W	NTC_ MODE	VBUS_ UV_THD		RESERV	'ED	VD	RV <sup>(7)</sup>	GI	PIO7 <sup>(7)</sup>			GPIO6	(7)		GPO5 <sup>(7)</sup>	
0F	PWR SHA	R/W		F	WR_SH	ARE_OU	JTPUT_THL	.D <sup>(7)</sup>				F	OWER	_SHAR	RE_TO_P	DP_THL	D <sup>(7)</sup>	
10	STATUS 1	R		PPS_OUTPUT_VOLTAGE    SHO					Y_PD_ CONN	LOAD _SHE _D DING								
11	STATUS 2	R	RES ERVE D	ERVE   CABLE   _MIS   OBJECT_POSITION   SINK_REQUEST_CURRENT_APDO   RESERV					RVED									
12	ID	R		VENDER									RVED					
14	CLK_ON	R/W			Enable o	ontrol of	the digital C	CLK: 0	x55AA	to enable	the digi	tal cloc	k, 0x000	00 to di	sable the	clock		

#### Note:

7) These registers are OTP-configurable. When the MPQ5031 VCC voltage rises above the UVLO rising threshold, the OTP contents are loaded to the I<sup>2</sup>C register.



# **REGISTER DESCRIPTION**

#### PDO\_TYPE

PDO1 is always enabled, and is fixed as a 5V fixed-power data object (PDO).

Address: 0x00 Type: Read/Write

Bits	Name	Description
D[15:10]	OTP_SOFTWARE_ REVISION_NO	Determined by MPS.
		Enables PDO5's power object. The bit is set to 1b by default.
D[7]	PDO5_EN	0b: Disabled 1b: Enabled
		Enables PDO4's power object. The bit is set to 1b by default.
D[6]	PDO4_EN	0b: Disabled 1b: Enabled
		Enables PDO3's power object. The bit is set to 1b by default.
D[5]	PDO3_EN	0b: Disabled 1b: Enabled
		Enables PDO2's power object. The bit is set to 1b by default.
D[4]	PDO2_EN	0b: Disabled 1b: Enabled
		Sets PDO5's power object. The bit is set to 1b by default.
D[3]	PDO5_TYPE	0b: Fixed PDO 1b: APDO
		Sets PDO4's power object. The bit is set to 0b by default.
D[2]	PDO4_TYPE	0b: Fixed PDO 1b: APDO
		Sets PDO3's power object. The bit is set to 0b by default.
D[1]	PDO3_TYPE	0b: Fixed PDO 1b: APDO
		Sets PDO2's power object. The bit is set to 0b by default.
D[0]	PDO2_TYPE	0b: Fixed PDO 1b: APDO

# PDO\_V1

Address: 0x01 Type: Read-Only

Bits	Name	Description
D[9:0]	PDO1_VOLTAGE_ SETTING	This bit sets PDO1's output voltage in 50mV units. Fixed to 0001 1001 00b (5V).



#### PDO\_I1

Address: 0x02 Type: Read/Write

Bits	Name	Description
D[15:10]	OTP_SUFFIX_CODE	Determined by MPS.
D[9:0]	PDO1_CURRENT_ SETTING	Sets PDO1's maximum output current in 10mA units. The default is 3A. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.

# PDO\_V2

Address: 0x03 Type: Read/Write

Default PDO TYPE: Fixed PDO

#### If PDO2\_TYPE is set to 0b (fixed PDO):

Bits	Name	Description
D[15:10]	RESERVED	Reserved. Set to 0b.
D[9:0]	PDO2_VOLTAGE_ SETTING	Sets PDO2's output voltage in 50mV units. The default is 9V.

#### If PDO2\_TYPE is set to 1b (APDO):

Bits	Name	Description
D[15:8]	PDO2_MAXIMUM_ VOLTAGE	Sets PDO2's maximum voltage in 100mV increments. The absolute maximum value is 21V.
D[7:0]	PDO2_MINIMUM_ VOLTAGE	Sets PDO2's minimum voltage in 100mV increments.

#### PDO\_I2

Address: 0x04 Type: Read/Write

Default PDO TYPE: Fixed PDO

#### If PDO2\_TYPE is set to 0b (fixed PDO):

Bits	Name	Description
D[15:10]	RESERVED	Reserved. Set to 0b.
D[9:0]	PDO2_CURRENT_SETTING	Sets PDO2's maximum output current setting in 10mA units. The default is 3A. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.

#### If PDO2\_TYPE is set to 1b (APDO):

Bits	Name	Description
D[15:7]	RESERVED	Reserved. Set to 0b.
D[6:0]	PDO2_CURRENT_ SETTING	Sets PDO2's maximum current in 50mA increments. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.



#### PDO\_V3

Address: 0x05 Type: Read/Write

Default PDO TYPE: Fixed PDO

#### If PDO3\_TYPE is set to 0b (fixed PDO):

Bits	Name	Description
D[15:10]	RESERVED	Reserved. Set to 0b.
D[9:0]	PDO3_VOLTAGE_ SETTING	Sets PDO3's output voltage in 50mV units. The default is 15V.

#### If PDO3\_TYPE is set to 1b (APDO):

Bits	Name	Description
D[15:8]	PDO3_MAXIMUM_ VOLTAGE	Sets PDO3's maximum voltage in 100mV increments. The absolute maximum value is 21V.
D[7:0]	PDO3_MINIMUM_ VOLTAGE	Sets PDO3's minimum voltage in 100mV increments.

#### PDO\_I3

Address: 0x06 Type: Read/Write

Default PDO TYPE: Fixed PDO

#### If PDO3\_TYPE is set to 0b (fixed PDO):

Bits	Name	Description
D[15:10]	RESERVED	Reserved. Set to 0b.
D[9:0]	PDO3_CURRENT_SETTING	Sets PDO3's maximum output current in 10mA units. The default is 3A. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.

#### If PDO3\_TYPE is set to 1b (APDO):

Bits	Name	Description
D[15:7]	RESERVED	Reserved. Set to 0b.
D[6:0]	PDO3_CURRENT_ SETTING	Sets PDO3's maximum current in 50mA increments. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If it is set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.

#### PDO\_V4

Address: 0x07 Type: Read/Write

Default PDO TYPE: Fixed PDO

#### If PDO4\_TYPE is set to 0b (fixed PDO):

Bits	Name	Description
D[15:10]	RESERVED	Reserved. Set to 0b.
D[9:0]	PDO4_VOLTAGE_ SETTING	Sets PDO4's output voltage in 50mV units. The default is 20V.



#### If PDO4\_TYPE is set to 1b (APDO):

Bits	Name	Description
D[15:8]	PDO4_MAXIMUM_VOLTAGE	Sets PDO4's maximum voltage in 100mV increments. The absolute maximum value is 21V.
D[7:0]	PDO4_MINIMUM_ VOLTAGE	Sets PDO4's minimum voltage in 100mV increments.

#### PDO\_I4

Address: 0x08 Type: Read/Write

Default PDO TYPE: Fixed PDO

#### If PDO4\_TYPE is set to 0b (fixed PDO):

Bits	Name	Description
D[15:10]	RESERVED	Reserved. Set to 0b.
D[9:0]	PDO4_CURRENT_ SETTING	Sets PDO4's maximum output current in 10mA units. The default is 3A. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.

#### If PDO4\_TYPE is set to 1b (APDO):

Bits	Name	Description
D[15:7]	RESERVED	Reserved. Set to 0b.
D[6:0]	PDO4_CURRENT_ SETTING	Sets PDO4's maximum current in 50mA increments. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.

#### PDO\_V5

Address: 0x09 Type: Read/Write

Default PDO TYPE: APDO

#### If PDO5\_TYPE is set to 0b (fixed PDO):

Bits	Name	Description
D[15:10]	RESERVED	Reserved. Set to 0b.
D[9:0]	PDO5_VOLTAGE_ SETTING	Sets PDO5's output voltage in 50mV units.

#### If PDO5\_TYPE is set to 1b (APDO):

Bits	Name	Description
D[15:8]	PDO5_MAXIMUM_ VOLTAGE	Sets PDO5's maximum voltage in 100mV increments. The default is 21V.
D[7:0]	PDO5_MINIMUM_ VOLTAGE	Sets PDO5's minimum voltage in 100mV increments. The default is 3.3V.

#### PDO\_I5

Address: 0x0A Type: Read/Write

Default PDO TYPE: APDO

If PDO5\_TYPE is set to 0b (fixed PDO):





Bits	Name	Description
D[15:10]	RESERVED	Reserved. Set to 0b.
D[9:0]	PDO5_CURRENT_ SETTING	Sets PDO5's maximum output current in 10mA units. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.

#### If PDO5\_TYPE is set to 1b (APDO) (default):

Bits	Name	Description
D[15:7]	RESERVED	Reserved. Set to 0b.
D[6:0]	PDO5_CURRENT_ SETTING	Sets PDO5's maximum current in 50mA increments. The default is 3A. When these bits are set >3A, the MPQ5031 first checks the cable current rating. If set to 5A, send a >3A setting. If the cable capability is 3A, only send a 3A maximum current capability.

#### CTL1

Address: 0x0B Type: Read/Write

Bits	Name	Description				
		Controls battery voltage low detection if GPIO2 or GPIO4 is set to VBATT_SENSE. These bits are set to 01b by default. These bits cannot be set to 11b. The table below lists the configurations.				
D[15]	VBATT_LOW_PULL _PS_EN	D[15]: VBATT_LOW_ PULL_PS_EN	0	0		1
D[8]	VBATT_LOW_PULL _NTC_EN	D[8]: VBATT_LOW_ PULL_NTC_EN	0	1		0
		PDO List when Battery Voltage Low Condition Occurs	PDO list is ba on register PDO_TYPE setting.	Update F	er PDOs pow	able the PDO with a rer rating equal to or exceeding R_SHARE_TO_PDP
		The MPQ5031 support BC1.2 DCP and Appl selections. These bits	le divider mod	le. The table be		
	LEGACY_ CHARGING_ MODE_SEL1 LEGACY_ CHARGING_ MODE_SEL0	D[14]: LEGACY_ CHARGING_ MODE_SEL_1	0	0	1	1
D[14] D[11]		D[11]: LEGACY_ CHARGING_ MODE_SEL_0	0	1	0	1
		DP/DM Charging Mode	All modes are active	Only DCP is active. No Apple divider mode or QC mode. Short the DP and DM pins.	Apple divider mode/DCP mode is active	Only DCP is active. No Apple divider mode or QC mode. Short the DP and DM pins.
		Enables the NTC2 pow	ver share functi	ion. This bit is se	t to 0b by defau	lt.
D[13]	NTC2_PS_EN	0: Disabled 1: Enabled				
		Enables CDP mode. To	his bit is set to	0b by default.		
D[12]	CDP_EN	0b: Non-CDP mode, ch 1b: CDP mode enabled divider, and DCP mode	d. The CDP pro	tocol is enabled	on the DP and	
D[10:9]	RESERVED	Reserved. Always write	e 00b to these	bits.		
D[7:4]	I2C_SLAVE_ ADDRESS	Sets the slave I <sup>2</sup> C add	ress. This bit is	set to 1000b by	default.	



D[3]	TYPE-C_MODE	Selection bit for 3A or 1.5A Type-C mode. This bit is set to 0b by default. In 5V/3A Type-C mode, the pull-up current (R <sub>P</sub> ) is 330µA, and the detection range (Rd) is between 0.8V and 2.6V.  0: 3A Type-C mode 1: 1.5A Type-C mode
	SLAVE_DEVICE_ SEL	Selects the power device that is incorporated with the MPQ5031. These bits are set to 001b by default.  000b: MPQ421x 001b: MPQ423x, MPQ426x 010b: MP28167-A 011b: MPQ4272-Page 0
D[2:0]		100b: MPQ4272-Page 0 100b: MPQ4272-Page 1 101b: For Non-I <sup>2</sup> C DC/DC converters. PDO2_SEL is pulled low when PDO2 is selected. PDO2_SEL and PDO3_SEL both pull low when PDO3 is selected. PDO2_SEL, PDO3_SEL, and PDO4_SEL all pull low when PDO4 is selected. EN_OUT = low, EN_OUT_MID = low during hard reset and detach events. For more details, see Figure 10 on page 20.  Others values are reserved.

#### CTL2

The message bits/bytes referenced in bits D[13:3] are defined in the USB Power Delivery Specification Revision 3.0, Version 2.0, which can be downloaded from the official USB website at https://usb.org/.

Address: 0x0C Type: Read/Write

Bits	Name	Description
		Sends the hard reset command. This bit is set to 0b by default.
D[15]	HDRST	0b: Normal state 1b: Send a hard reset command to the sink. After the HDRST message is sent, this bit auto-resets to 0b
	SEND_SRC_CAP	Sends the source capability command. The PD engine only sends a SOURCE_CAP message while in the ready state. This bit is set to 0b by default.
D[14]		0b: Normal state 1b: Send source capability. After SOURCE_CAP is sent, this bit auto-resets to 0b
-[]		When there is a PDO configuration change in I <sup>2</sup> C registers 0x01~0x09, SEND_SRC_CAP should be set to make the new PDO take effect. After sending a new source capability, the MPQ5031 clears this bit. Change the 0x00 register for the new PDO to take effect immediately.
D[13]	USB SUSPEND	Sets whether USB suspend functions are supported. This bit is set to 0b by default. This bit is defined in Fixed Supply PDO message bit[28].
נרוטן		0b: USB suspend is not supported 1b: USB suspend is supported
DIASI	USBCOMMUNICATE	Sets whether USB communication capabilities are supported. This bit is set to 0b by default. This bit is defined in Fixed Supply PDO message bit[26].
D[12]	USBCOMMUNICATE	0b: USB communication capabilities are not supported 1b: USB communication capabilities are supported
D[11:9]	LPS	LPS compliant when set. These bits are defined in SOURCE_CAPABILITIES_EXTENDED Message byte 12, bits[2:0]. These bits are set to 101b by default.
		D[11] = LPS bit D[10] = PS1 bit D[9] = PS2 bit





D[8:6]	TOUCH_CURRENT	Sets the touch current, bits[2:0]. These bits are defined in SOURCE_CAPABILITIES_EXTENDED Message byte 13, bits[2:0]. These bits are set to 000b by default. D[8] indicates touch current bit[2].
D[5:4]	TOUCH_TEMP	Sets the touch temperature default value to 0, 1, or 2. These bits are defined in SOURCE_CAPABILITIES_EXTENDED Message byte 20, bits[1:0]. These bits are set to 00b by default.
D[3]	UNCUKEXTMSG	Sets the unchunked extend message bit. This bit is defined in Fixed Supply PDO message bit[24]. This bit is set to 1b by default.
D[2]	RESERVED	Reserved. Always write 0b to this bit.
D[4]	SRC CAP	Send source capability twice control bit when a PD2.0 device is attached. This bit is set to 0b by default.
D[1]	SRC_CAP	Send source capability twice     Send source capability once
D[0]	VDRV_EN	Enables VDRV functions. This bit is set to 0b by default.
		0b: Disable the VDRV output. VDRV has $5.1k\Omega$ pull-down resistor when it is disabled 1b: Enable VDRV functions

#### CTL3

Address: 0x0D Type: Read/Write

Bits	Name	Description
		Sets the MP28167-A and MPQ421x operation modes. This bit is set to 1b by default.
D[15]	PFM_PWM	0b: PFM mode. If the MP28167-A is selected as the $I^2C$ slave, the MP28167-A's 0x04 register D[4] = 0. If the MPQ421x is selected as the $I^2C$ slave, the MPQ421x's 0x02 register D[2] = 0. 1b: PWM mode. If the MP28167-A is selected as the $I^2C$ slave, then 0x04 register D[4] = 1. If the MPQ421x is selected as the $I^2C$ slave, then the its 0x02 register D[2] = 1
		Enables frequency dithering for the MPQ421x. This bit is set to 0b by default.
D[14]	FREQ_DITHER	0b: Disabled (fixed-frequency mode). If the MPQ421x is selected as the $I^2C$ slave, the MPQ421x's 0x02 register D[4] = 0 1b: Enabled. If the MPQ421x is selected as the $I^2C$ slave, the MPQ421x's 0x02 register D[4] = 1. For other devices like the MPQ4230, ignore this bit
		Sets the EN off time delay. Only valid when GPIO4 is set for EN functions. These bits are set to 010b by default.
D[13:11]	EN_OFF_TIMER	000b: No delay 001b: 10 minutes 010b: 22 minutes 011b: 40 minutes 100b: 80 minutes 101b: 120 minutes
		Configures the function of the GPIO4 pin. These bits are set to 00b by default.
D[10:9]	GPIO4	00b: Reserved. This pin can be floated or tied to ground 01b: EN function. When the external input is >1.4V, the MPQ5031 is enabled. When the external input is <1.2V, the MPQ5031 is disabled in a low I <sub>Q</sub> state. EN_OFF_TIMER can configure the off delay 10b: NTC2 function. Refer to the NTC2 description on page 22. 11b: The GPIO4 pin functions as the VBATT_SENSE pin, and monitors the battery voltage. If the battery voltage is low (resistor divider ratio is 1/10), then the PD updates the source capability. The internal comparator falling threshold is 1.1V, and the rising threshold is 1.15V with a 20μs deglitch time. This comparator operates when VCC exceeds the under-voltage lockout (UVLO) threshold after a 5s delay time



		Configures the function of GPIO3 pin. This low-voltage pin supports 5.5V operation and has an internal ESD Zener diode. These bits are set to 000b by default.
D[8:6]	GPIO3	000b: I2C_ARB function. Tri-state input or output to avoid having two I²C masters. This function has a similar structure to GPIO2 when it is set to PWE_SHARE. See the I²C Arbitration section on page 23 for more details 001b: EN function. When the external input is >1.4V, the MPQ5031 is enabled. When the external input is <1.2V, the MPQ5031 is disabled in a low Iq state 010b: ATTACH function. GPIO3 is pulled low once a Type-C port is attached. Open-drain structure 011b: EN_OFF_DELAY_OUT function. When EN goes low, this pin still outputs high. It changes to a floating state after 22 minutes. This signal can be used to control the upstream DC/DC converter's enable pin 100b: POL output 101b: PDO3_SEL_OUT. This is an open-drain output. When PDO3 is selected, this pin pulls low. The pull-down speed is very slow (typically 1ms to drop from 100k $\Omega$ to $2\Omega$ ) 110b: ISENS+ function. This pin is used for line drop compensation when the MPQ4214 is selected. Connect ISENS+ to the MPQ4214's COMP pin to sense current information 111b: IPWM function. The PWM output sets the external buck-boost's PPS CC current limit. This pin must be pulled up externally. The PWM signal frequency is 10kHz
		Configures the function of the GPIO2 pin. This is a low-voltage pin. These bits are set to 110b by default.
D[5:3]	GPIO2	000b: QC_12 function. For QC2.0 mode, this pin is used to enable QC 12Vout 001b: POL output. This is an open-drain output to indicate the plug orientation. When CC1 is selected as the CC line, the POL is pulled low. When CC2 is selected as the CC line, the POL is an open drain 010b: GPIO2 is pulled low 110b: PWR_SHARE function. See the Power Sharing Function section on page 23 for more details 111b: VBATT_SENSE pin
		Configures the function of the GPIO1 pin. It is a low-voltage pin that supports 5.5V operation. These bits are set to 001b by default.
D[2:0]	GPIO1	000b: PDO2_SEL_OUT. This pin is an open-drain output. When PDO2 is selected, this pin is pulled low. The pull-down speed is very slow (typically 1ms to drop from $100k\Omega$ to $2\Omega$ ). For QC2.0 mode, this pin is used to enable $9V_{OUT}$ (QC logic adds this output signal as well) 001b: Interrupt input pin. This is a high-impedance pin that monitors the input signal. In real applications, it should be connected to the external DC/DC converter's ALT pin to get interruption information from the $I^2C$ slave 010b: GPIO1 is pulled low 011b: GPIO1 is an open drain 100b: VSEL1. Output voltage selection pin. See the GPIO Summary section on page 38 for more details $I_{OUD} = I_{OUD} = I_{$

# CTL4

Address: 0x0E Type: Read/Write

Bits	Name	Description
		Sets the NTC behavior. This bit is set to 0b by default.
D[15]	NTC_MODE	0b: If NTC is triggered, the MPQ5031 initiates load-shedding 1b: If NTC is triggered, the MPQ5031 shuts down. This process is similar to internal thermal shutdown, and the ENO_MID output is set



		Sets the VBUS_P under-voltage (UV) threshold. Set the threshold to 2.97V when the minimum APDO voltage is 3.3V, and to 4.5V when the minimum APDO voltage is 5V. This
D[14]	VBUS_UV_THD	bit is set to 0b by default.
		0b: The VBUS_P falling threshold is 2.97V 1b: The VBUS_P falling threshold is 4.5V
		Sets the VDRV pin function. These bits are set to 00b by default.
D[10:9]	VDRV	00b: VDRV function. This pin is the external N-channel MOSFET gate driver signal. When the sink is attached, VDRV drives the external N-channel MOSFET to turn on. Then power will flow from the DC/DC output to the sink. When the sink is detached, VDRV drives the external N-channel MOSFET to turn off to isolate the power path 01b: VDRV1 function. See Figure 10 on page 20 for the timing sequence
		Configures the GPIO7 pin. It is a low-voltage pin. These bits are set to 011b by default.
D[8:6]	GPIO7	000b: DISCHG pin. Output discharge function. The discharge function only turns on for 200ms, then turns off. DISCHG only outputs a control signal. An external N-channel MOSFET should be added between VBUS and GND for this function 001b: ATTACH function. This pin is pulled low once a Type-C port is attached. Open-drain structure 011b: EN_OUT_MID function. If there is a hard reset or a detach event, this pin clamps the voltage to 1V 100b: EN_OUT. This output controls the upstream DC/DC output. If a hard reset occurs, the PD engine pulls this pin to GND. In normal operation, this pin is an open drain output 101b: ADJ function. This function is used for MPQ421x line drop compensation. It sinks a 2 $\mu$ A current when the COMP voltage >1.2V
		Configures the GPIO6 pin. These bits are set to 110b by default.
D[5:3]	GPIO6	000b: PDO4_SEL_OUT. When PDO4 is selected, this bit is an open drain output 001b: VSEL2. Output voltage selection pin 010b: POL output. Open-drain output to indicate the plug orientation. If CC1 is selected as the CC line, then the POL is pulled low. If CC2 is selected as the CC line, then the POL is an open drain 011b: EN function. When the external input is >1.4V, the MPQ5031 is enabled. When the external input is <1.2V, the MPQ5031 is disabled in a low Io state 100b: SYNC_OUT2. PWM output to sync external buck-boost's switching frequency. It is an open-drain output with a 25% duty cycle, 450kHz frequency, and 180° phase delay based on GPIO5 101b: NTC2 function. See the NTC2 description on page 22 for more details 110b: I2C_SLV_SDA. This pin is an I²C slave data pin
		Configures the GPIO5 pin. These bits are set to 000b by default.
D[2:0]	GPIO5	000b: I2C_SLV_SCL. This pin is the I²C slave's clock pin 001b: IPWM. The PWM output sets the external buck-boost's PPS CC current limit. It should be internally pulled up to 1.8V with a $2k\Omega$ resistor. The PWM signal frequency is 10kHz 010b: SYNC_OUT1. This is the PWM output to sync the external buck-boost's switching frequency. It is an open-drain output with a 25% duty cycle, 250kHz frequency, and 0° phase delay 011b: This is the PWM output to sync the external buck-boost's switching frequency. It is an open-drain output with a 25% duty cycle, 350kHz frequency, and 0° phase delay 100b: SYNC_OUT1. This is the PWM output to sync the external buck-boost's switching frequency. It is an open-drain output with a 25% duty cycle, 450kHz frequency, and 0° phase delay 101b: ATTACH function. This pin is pulled low once a Type-C port is attached. It has an open drain structure 111b: VBUS_UV_FIXPDO. This pin is a VBUS voltage detection input. Connect a 1/5 resistor divider to VBUS



#### **PWRSHA**

Address: 0x0F Type: Read/Write

Bits	Name	Description
D[15:8]	PWR_SHARE_ OUTPUT_THLD	Sets the threshold of the sink-requested PDO power rating. If the sink-requested PDO power rating is equal to or higher than this threshold, the GPIO2 pin (if GPIO2 is set to PWR_SHARE) pulls low. The default value is 0x3C (60W).  0x01: 1W  0xFF: 255W
D[7:0]	PWR_SHARE_ INPUT_TO_PDP_ THLD	Sets the port's PD power rating. If the GPIO2 pin (if GPIO2 is set to PWR_SHARE) is pulled low, the battery voltage is low (VBATT_LOW_PULL_PS_EN = 1b), or NTC2 is triggered (NTC2_PS_EN = 1b), all PDOs with a power rating equal to or higher than this threshold are disabled. The default value is 0x3C (60W).  0x01: 1W 0xFF: 255W

#### STATUS1

Address: 0x10 Type: Read-Only

This register is read clear.

Bits	Name	Description
D[15:5]	PPS_OUTPUT_ VOLTAGE	Records the sink requested for PPS VOUT. In 20mV. This bit is only valid when the selected PDO is APDO.
D[4]	BATTERY_ SHORT	This bit is set if CCx, DP, or DM is shorted to the input battery.
D[3]	ANALOG_ DETECTED_ TYPEC	Detects if a Type-C device is attached or unattached.
D[2]	ANA_OTP	Indicates if the MPQ5031 enters over-temperature protection (OTP), excluding thermal shutdowns caused by NTC or NTC2. It also indicates if the external power device enters OTP (the digital side provides the OTP information for the external device).
D[1]	PREVIOUSLY_ PD_ CONNECTED	Indicates whether the MPQ5031 has a PD contract.
D[0]	LOAD_ SHEDDING	Indicates if the device has entered load-shedding (see Figure 12 on page 22 for more details).

#### STATUS2

Address: 0x11 Type: Read-Only Read clear.

Bits	Name	Description
D[15]	RESERVED	Reserved.
D[14]	CABLE_CAP	1b: The cable can handle 5A 0b: The cable can only handle 3A
D[13]	CAPABILITY_ MISMATCH	A sink request sets the "Capability Mismatch" bit.





D[12:10]	OBJECT_ POSITION	When a sink is attached, these bits indicate the sink-requested PDO position.  000b: Non-PD device is attached 001b: Sink requested PDO1 (5V PDO) 010b: Sink requested PDO2 011b: Sink requested PDO3 100b: Sink requested PDO4 101b: Sink requested PDO5
D[9:2]	SINK_REQUEST _CURRENT_ APDO	Sink-requested APDO current in 50mA units.
D[1:0]	RESERVED	Reserved.

#### ID

Address: 0x12 Type: Read-Only

Bits	Name	Description
D[15:12]	VENDOR_ID	Vendor ID. The default is 1000b.
D[11:0]	RESERVED	Reserved.

# CLK\_ON

Address: 0x14 Type: Read/Write

Bits	Name	Description
		Enables the digital CLK. Set these bits to 0x55AA to enable the digital clock; set them to 0x0000 to disable the clock.
D[15:0]	CLK_ON	When GPIO5 and GPIO6 are configured as I2C_SLV_SCL and I2C_SLV_SDA, the digital CLK should be enabled when sending I²C write commands via GPIO5/GPIO6, then the digital CLK should be disabled after the I²C command ends. A digital CLK does not need to be enabled when only reading the I²C register via GPIO5 and GPIO6.



#### I<sup>2</sup>C Bus Slave Address

The slave address is a 7-bit address followed by an 8th data direction bit (read or write). The A4 to A1 bits are configurable via the OTP.

	<b>A7</b>	A6	<b>A5</b>	A4	А3	A2	A1
Setting Value	0	1	0	1 (8)	0 (8)	0 (8)	0 (8)

#### Note:

8) By default, the slave address is 0x28, A[7:1] = 0101000.

#### **GPIO Summary**

For more details on the GPIO functions, see the CTL3 register on page 33 and the CTL4 register on page 34.

Name	Function Options							
GPIO1	INT	PDO2_ SEL_OUT	VSEL1	-	-	-	-	-
GPIO2	PWR_ SHARE	QC_12	POL	VBATT_ SENSE	•	•	-	-
GPIO3	I2C_ARB	PDO3_ SEL_OUT	POL	EN_OFF_ DELAY_ OUT	ISENS+	IPWM <sup>(9)</sup>	ATTACH	EN
GPIO4	EN	NTC2	VBATT_ SENSE	-	-	-	-	-
GPIO5	SYNC_ OUT1	IPWM <sup>(9)</sup>	VBUS_ UV_ FIXPDO	I2C_SLV_ SCL	ATTACH	-	-	-
GPIO6	SYNC_ OUT2	PDO4_ SEL_OUT	VSEL2	I2C_SLV_ SDA	NTC2	POL	EN	-
GPIO7	DISCHG	EN_OUT	EN_OUT_ MID	ADJ	ATTACH	-	-	-
VDRV	VDRV	VDRV1	-	-	-	-	-	-

#### Note:

9) IPWM on GPIO3 must be pulled up externally. IPWM on GPIO5 is pulled up internally.



Table 8: Vout Voltage vs. GPIO Output for Non-I<sup>2</sup>C DC/DC Converter Use Case

V <sub>OUT</sub>	PDO2_SEL_OUT (or QC_9)	QC_12	PDO3_SEL_OUT	PDO4_SEL_OUT
5V	Open drain	Open drain	Open drain	Open drain
9V	0	Open drain	Open drain	Open drain
12V	0	0	Open drain	Open drain
15V	0	Open drain	0	Open drain
20V	0	Open drain	0	0

Table 9: Vout Voltage vs. VSEL1, VSEL2 Output Status (10)

V <sub>OUT</sub>	VSEL1	VSEL2				
5V	Open drain	Open drain				
9V	0	Open drain				
15V	Open drain	0				
20V	0	0				
12V	100kΩ to GND	0				

#### Notes:

10) VSEL1 and VSEL2 can be used to control the MP2491C's output voltage.



#### APPLICATION INFORMATION

# PCB Layout Guidelines (11)

Efficient PCB layout is critical for stable operation and better ESD performance. A 2-layer or 4-layer layout is recommended. For the best results, refer to Figure 19 and follow the guidelines below:

 Place the VCC and VDD decoupling capacitor as close to the VCC and VDD pins as possible.

- 2. Put 9 vias on the exposed pad of the IC. Connect the exposed pad to ground.
- Place the ESD diodes as close to the IC as possible. Use short, direct, and wide traces to connect CC1, CC2, DP, and DM to the cathode of ESD diodes. Connect the anode of ESD diode to ground with multiple vias.
- 4. Use short, direct, and wide traces to connect CC1 and CC2 to the USB Type-C receptacle.

#### Notes:

11) The recommended layout is based on Figure 20 on page 41.

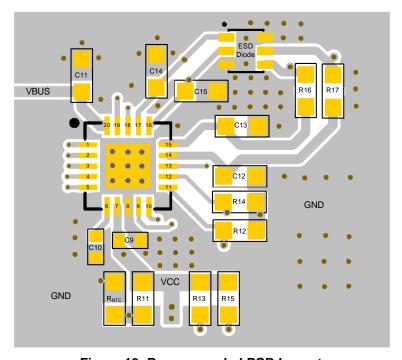


Figure 19: Recommended PCB Layout



### TYPICAL APPLICATION CIRCUITS

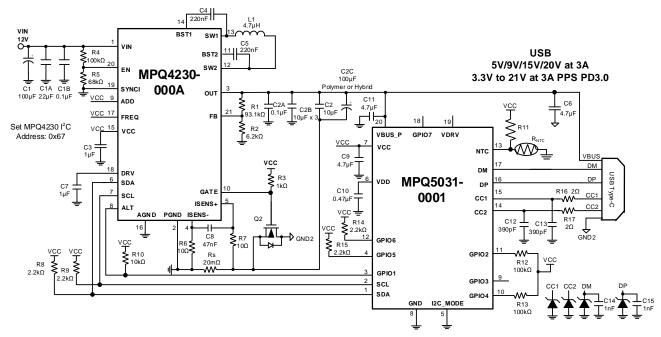


Figure 20: MPQ4230 + MPQ5031 for 60W PD Application (12)

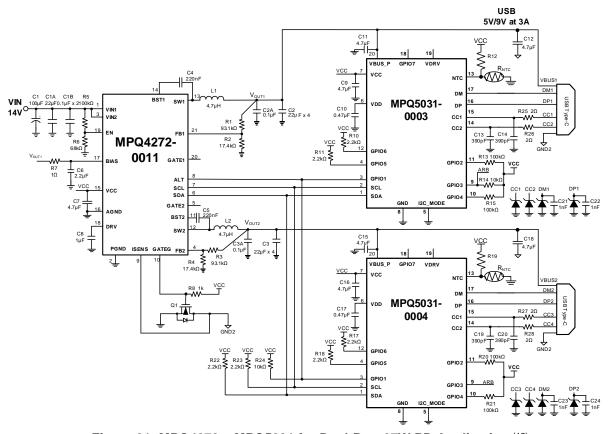


Figure 21: MPQ4272 + MPQ5031 for Dual-Port 27W PD Application (12)

12) A TVS and RC filter should be added to the DP/DM/CCx pins to ensure that they pass ±8kV/±15kV IEC Contact/Air Discharge ESD.



# **MPQ5031GRE-0001 CONFIGURATION TABLE**

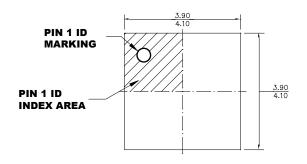
OTP Items	Enabled/Disabled	PDO Type	Voltage	Current
PDO1	Enabled	Fixed PDO	5V	3A
PDO2	1b: Enabled (default)	0b: Fixed PDO (default)	9V (default)	3A
PDO3	1b: Enabled (default)	0b: Fixed PDO (default)	15V (default)	3A
PDO4	1b: Enabled (default)	0b: Fixed PDO (default)	20V (default)	3A
PDO5	1b: Enabled (default)	1b: APDO (default)	3.3V to 21V (default)	3A

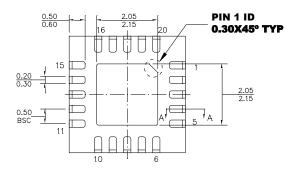
OTP Items	Description	Value
GPIO1	Configures the function of the GPIO1 pin.	001b: Interrupt input pin (default)
GPIO2	Configures the function of the GPIO2 pin.	110b: PWR_SHARE function (default)
GPIO3	Configures the function of the GPIO3 pin.	000b: I2C_ARB function (default)
GPIO4	Configures the function of the GPIO4 pin.	00b: Reserved (default)
GPIO5	Configures the function of the GPIO5 pin.	000b: I2C_SLV_SCL (default)
GPIO6	Configures the function of the GPIO6 pin.	110b: I2C_SLV_SDA (default)
GPIO7	Configures the function of the GPIO7 pin.	011b: EN_OUT_MID function (default)
VBATT_LOW_PULL_PS _EN	The PDO list is reduced based on PWR_SHARE_TO_PDP_THLD when a battery voltage low condition is triggered.	0b: Disabled (default)
VBATT_LOW_PULL_ NTC_EN	Update the PDO list to 5V/2A. Other PDOs are disabled when a battery voltage low condition is triggered.	0b: Disabled
NTC2_PS_EN	Connect NTC2 to power share control.	0b: Disabled (default)
LEGACY_CHARGING_ MODE_SEL	QC3.0/DCP short mode/Apple divider mode selection.	00b: All modes are active
CDP_EN	Enables for CDP mode.	0b: Non-CDP mode, charging only protocol on DP, DM pins (default)
I2C_SLAVE_ADDRESS	Sets the MPQ5031's I <sup>2</sup> C slave address.	28H (default)
TYPE-C_MODE	Selects 3A or 1.5A Type-C mode.	0b: 3A Type-C mode (default)
SLAVE_DEVICE_SEL	Selects the power device incorporated with MPQ5031.	001b: MPQ423x, MPQ426x (default)
VDRV	Sets the VDRV pin function.	00b: VDRV function (default)
VDRV_EN	Enables the VDRV function.	0b: Disabled (default)
PFM_PWM	Sets the MP28167A and MPQ421x operation mode.	1b: PWM mode (default)
FREQ_DITHER	Enables frequency dithering for the MPQ421x.	0b: Fixed frequency mode (default)
EN_OFF_TIMER	Sets different EN off timers. Only valid when GPIO4 is set for EN functions.	010b: 20 minutes (default)
NTC_MODE	Sets the MPQ5031 behavior when NTC is triggered.	1b: The MPQ5031 shuts down
VBUS_UV_THD	Set the VBUS_P UV threshold.	0b: VBUS_P falling threshold is 2.97V (default)
PWR_SHARE_OUTPUT _THLD	Sets the sink-requested PDO power rating threshold.	60W (default)
PWR_SHARE_TO_PDP _THLD	Sets the threshold for PDO power rating.	60W (default)
USB SUSPEND	USB Suspend supported or not.	0b: Not supported (default)
USBCOMMUNICATE	USB Communication Capable or not.	0b: Not supported (default)
LPS	LPS compliant when set.	101b (default)
TOUCH_CURRENT	Sets the touch current bits[2:0].	000b (default)
TOUCH_TEMP	Sets the touch temperature default value to 0, 1, or 2.	00b (default)
UNCUKEXTMSG	Sets unchunked extend message bit.	1b (default)
OTP_SUFFIX_CODE	OTP suffix code.	0x0001



# **PACKAGE INFORMATION**

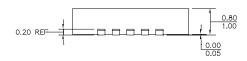
# QFN-20 (4mmx4mm)



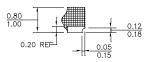


#### **TOP VIEW**

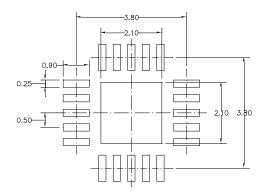
**BOTTOM VIEW** 



**SIDE VIEW** 



**SECTION A-A** 



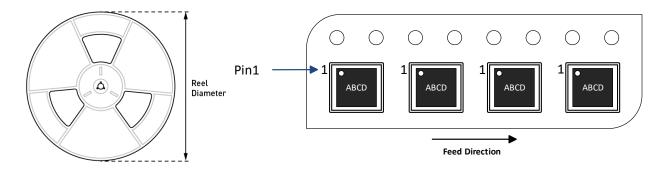
**RECOMMENDED LAND PATTERN** 

#### NOTE:

- 1) THE LEAD SIDE IS WETTABLE.
- 2) ALL DIMENSIONS ARE IN MILLIMETERS.
- 3) EXPOSED PADDLE SIZE DOES NOT INCLUDE MOLD FLASH.
- 4) LEAD COPLANARITY SHALL BE 0.08 MILLIMETERS MAX.
- 5) JEDEC REFERENCE IS MO-220
- 6) DRAWING IS NOT TO SCALE.



# **CARRIER INFORMATION**



Part Number	Package Description	Quantity/ Reel	Quantity/ Tube	Quantity/ Tray	Reel Diameter	Carrier Tape Width	Carrier Tape Pitch
MPQ5031GRE- xxxx-AEC1–Z	QFN-20 (4mmx4mm)	5000	N/A	N/A	13in	12mm	8mm



# **REVISION HISTORY**

Revision #	Revision Date	Description	Pages Updated
1.0	12/15/2020	Initial Release	-

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